

AMENDMENTS TO THE CLAIMS

1. (Currently Amended) An image processing apparatus, comprising:

an image data input unit for inputting image data of ~~an~~ a plurality of object objects including a main subject;

a range setting unit for restricting a searching range in the depth direction for searching a said main object subject from the plurality of object objects using the input image data; and

a partial image extracting unit for extracting a partial image including said main subject from said image data based on depth distribution information indicating a distance to each of said plurality of objects included in said image data, the part of an object included in a depth direction of said partial image being restricted to said searching range as a partial image set by said range setting unit.

2. (Currently Amended) The image processing apparatus as claimed in claim 1, wherein said image data input unit comprises a means for inputting a parallax image, which picks up an image of said plurality of object objects from a plurality of different perspectives, and the image processing apparatus further comprises a depth distribution information receiving unit for receiving said depth distribution information based on said parallax image.

3. (Currently Amended) The image processing apparatus as claimed in claim 1, further comprising a main subject detecting unit for detecting a said main subject from said partial image and receiving main subject information.

4. (Original) The image processing apparatus as claimed in claim 3, wherein said main subject detecting unit comprises:

a distinctive parts detecting unit for detecting from said partial image, a distinctive part, which should be included in said main subject; and

an information receiving unit for receiving said main subject information based on the position of said distinctive part detected by said distinctive parts detecting unit.

5. (Currently Amended) The image processing apparatus as claimed in claim 3, wherein: said range setting unit comprises a means for setting a first searching range and a means for setting a second searching range, which differs from said first searching range;

said partial image extracting unit comprises a means for extracting ~~the part of~~ at least one of said plurality of object objects included in said first searching range as a partial image and a means for extracting ~~the part of~~ at least one of said plurality of object objects included in said second searching range as a second partial image; and

said main subject detecting unit comprises a means for detecting said main subject from said first partial image and a means for detecting said main subject from said second partial image when said main subject is not detected from said first partial image.

6. (Original) The image processing apparatus as claimed in claim 5, wherein said range setting unit sets a predetermined depth length as said first searching range and sets the depth length contiguous to said first searching range as said second searching range.

7. (Original) The image processing apparatus as claimed in claim 5, wherein said range setting unit sets the depth length, which includes an independent object existing at the nearest distance, as said first searching range based on said depth distribution information and sets the depth length contiguous to said first searching range as said second searching range.

8. (Currently Amended) The image processing apparatus as claimed in claim 3, wherein
said range setting unit divides the depth range that includes said plurality of object
objects in said image data based on said depth distribution information and sets a plurality of said
searching ranges;

said partial image extracting unit extracts from said image data, ~~the part of~~ at least one of
said plurality of object objects included in each of a plurality of said searching ranges as a
plurality of said partial image; and

said main subject detecting unit detects said main subject from each of a plurality of said
partial image and receives a plurality of said main subject information.

9. (Original) The image processing apparatus as claimed in claim 3, wherein:
said range setting unit sets a different said searching range when said main subject is not
detected in said searching range set by said range setting unit;
said partial image extracting unit extracts again said partial image; and
said main subject detecting unit detects again said main subject.

10. (Currently Amended) The image processing apparatus as claimed in claim 3,
wherein said image data input unit is an image capturing unit for picking up an image of said
plurality of object objects, comprising:

a photographic condition setting unit for setting a photographic condition based on said
main subject information; and

an image capturing control unit for controlling imaging by said image capturing unit
based on said photographic condition.

11. (Withdrawn) The image processing apparatus as claimed in claim 3, further comprising:

a processing condition setting unit for setting an image processing condition based on said main subject information; and

an image processor for processing said image data based on said image processing condition.

12. (Withdrawn) The image processing apparatus as claimed in claim 3, further comprising:

an output condition setting unit for setting an image outputting condition based on said main subject information; and

an image data output unit for outputting said image data based on said image outputting condition.

13. (Withdrawn – Currently Amended) The image processing apparatus as claimed in claim 3, further comprising:

a selecting condition storing unit for storing a predetermined selecting condition of which said main subject should ~~satisfies~~ satisfy; and

an image selecting unit for selecting from a plurality of said image data input by said image data input unit, a desired image data, which includes a desired main subject satisfying said selecting condition.

14. (Currently Amended) The image processing apparatus as claimed in claim 3, wherein said image data input unit is an image capturing unit, which captures an image of said plurality of object ~~objects~~ based on a photographic timing signal, comprising:

a timing condition storing unit for storing a predetermined photographic timing condition relating to said main subject; and

a timing signal output unit for outputting said photographic timing signal to said image capturing unit when said main subject satisfies said photographic timing condition.

15. (Withdrawn - Currently Amended) The image processing apparatus as claimed in claim 1, further comprising a distance measuring unit which comprises:

a light irradiating section for irradiating light to said plurality of ~~object~~ objects; and

a calculating section for calculating a distance from said light irradiating section to said plurality of ~~object~~ objects on the basis of the intensity of light reflected from said plurality of ~~object~~ objects, wherein said distance measuring unit outputs a distance information to said range setting unit.

16. (Withdrawn) The image processing apparatus as claimed in claim 15, wherein said light irradiating section comprises a first light source irradiating light having a first wavelength and a second light source irradiating lights having a second and a third wavelengths, and said first and second light sources are located at an optically different positions.

17. (Withdrawn) The image processing apparatus as claimed in claim 16, wherein said first and second light sources irradiate lights at the same timing.

18. (Withdrawn - Currently Amended) The image processing apparatus as claimed in claim 17, further comprising:

an optically focusing section for focusing the lights irradiated by light irradiating unit and reflected from said plurality of object objects;

a beam splitting section for optically splitting said reflected light into a first light having said first wavelength, a second light having said second wavelength and a third light having said third wavelength;

a light receiving section for receiving said reflected lights split by said beam splitting section; and

a light intensity detecting section for detecting a light intensity of said first, second and third reflected lights received by said light receiving section,

wherein said calculating section calculates out a distance from said plurality of object objects on the basis of said light intensity detected by said light intensity detecting section.

19. (Withdrawn - Currently Amended) The image processing apparatus as claimed in claim 15, wherein said light irradiating section irradiates a light beam, further comprising:

a light beam scanning section for scanning around a startpoint said light beam toward a predetermined object within said plurality of object objects; and

a reflected light beam detecting section for detecting light beams reflected by a target of said plurality of object objects, wherein said calculating section comprises an integrating section for calculating an amount of integrated intensity of said reflected light beams from said target of said plurality of object objects and a distance calculating section for calculating said distance on the basis of said integrated intensity and said peak intensity of said reflected light.

20. (Withdrawn) The image processing apparatus as claimed in claim 1, further comprising a mode selecting unit for selecting an operation mode corresponding to an intended

object, wherein said range setting unit restricts said searching range on the basis of said selected operation mode, and said partial image extracting unit extracts said partial image on the basis of said selected operation mode.

21. (Withdrawn - Currently Amended) The image processing apparatus as claimed in claim 1 or 20, further comprising a display unit for displaying said partial image extracted by said partial image extracting unit and a changing section for changing a candidate of said ~~object~~ main subject selected by said partial image extracting unit.

22. (Currently Amended) An image processing method, comprising:
inputting image data of ~~an~~ a plurality of object objects;
setting a searching range, which defines a depth length for searching a main subject in said image data;
extracting a partial image including said main subject from said image data based on depth distribution information indicating a distance to each of said plurality of objects included in said image data, a depth direction of said partial image being restricted to said searching range, ~~the part of said object included in said searching range as a partial image, based on a depth distribution information showing the distance between a camera and each part of said object included in said image data~~;
detecting said main subject in said partial image; and
receiving a predetermined main subject information relating to the detected said main subject.

23. (Currently Amended) The image processing method as claimed in claim 22, wherein:

said setting is a first setting of a first searching range as said searching range;

said extracting is a first extracting of ~~the part of~~ at least one of said plurality of object objects included in said first searching range, as a first partial image; and

said detecting is a first detecting of said main subject in said first partial image, said detecting comprising:

a second setting of a second searching range as said searching range when said main subject is not detected in said first partial image;

a second extracting of ~~the part of~~ at least one of said plurality of object objects included in said second searching range as a second partial image; and

a second detecting of said main subject in said second partial image.

24. (Original) The image processing method as claimed in claim 23, wherein:

said first setting is a setting of the depth length that includes an independent object existing at the nearest distance as said first searching range based on said depth distribution information; and

said second setting is a setting of the depth length contiguous to said first searching range, as said second searching range.

25. (Currently Amended) The image processing method as claimed in claim 22, wherein:

said setting is a dividing the depth range that includes said plurality of object objects in said image data based on said depth distribution information and a setting of a plurality of said searching range;

said extracting is a extracting from said image data, of ~~the part of~~ at least one of said plurality of object objects included in each of a plurality of said searching range as a plurality of said partial image;

said detecting is a detecting of said main subject from each of a plurality of said partial image; and

said receiving is a receiving of said main subject information relating to each of a plurality of the detected said searching range.

26. (Currently Amended) The image processing method as claimed in claim 22, wherein said inputting is an inputting at an image capturing unit, which captures an image of said plurality of object objects, comprising:

deciding a photographic condition based on said main subject information; and

controlling an image capturing at said image capturing unit based on said photographic condition.

27. (Withdrawn) The image processing method as claimed in claim 22, further comprising:

setting an image processing condition based on said main subject information; and

processing said image data based on said image processing condition.

28. (Withdrawn) The image processing method as claimed in claim 22, further comprising:

setting an image outputting condition based on said main subject information;
outputting said image data based on said image outputting condition,

29. (Withdrawn) The image processing method as claimed in claim 22, further comprising:

storing a predetermined selecting condition relating to said main subject; and
selecting from a plurality of said image data input at said inputting, a desired image data that includes a desired main subject satisfying said selecting condition.

30. (Currently Amended) The image processing method as claimed in claim 22, wherein said inputting is a capturing of an image of said plurality of object objects based on a photographic timing signal, further comprising:

storing a predetermined photographic timing condition relating to said main subject; and
outputting said photographic timing signal to said image capturing unit when said main subject satisfies said photographic timing condition.

31. (Withdrawn - Currently Amended) A recording medium, which records thereon a program for processing an image and can be read by a computer, comprising:

a module for inputting image data of a subject;
a module for setting a searching range, which defines the depth length for searching a main subject in said image data;

a module for extracting from said image data, ~~the part of said~~ ~~the part of~~ at least one of said plurality of ~~object~~ objects included in said searching range as a partial image, based on depth distribution information showing the distance between a camera and said plurality of ~~object~~ objects included in said image data;

~~a module for~~ detecting said main subject from said partial image; and

~~a module for~~ receiving predetermined main subject information relating to detected said main subject.

32. (New) A computer program product comprising a recording medium, having recorded thereon a program for processing an image, by performing the operations of:

inputting image data of a plurality of objects;

setting a searching range, which defines the depth length for searching a main subject in said image data;

extracting a partial image including said main subject from said image data based on depth distribution information indicating a distance to each of said plurality of objects included in said image data, a depth direction of said partial image being restricted to said searching range;

detecting said main subject from said partial image; and

receiving predetermined main subject information relating to detected said main subject.